

Approximation Schemes for Geometric Coverage Problems

Minati De

Indian Institute of Technology Delhi, India

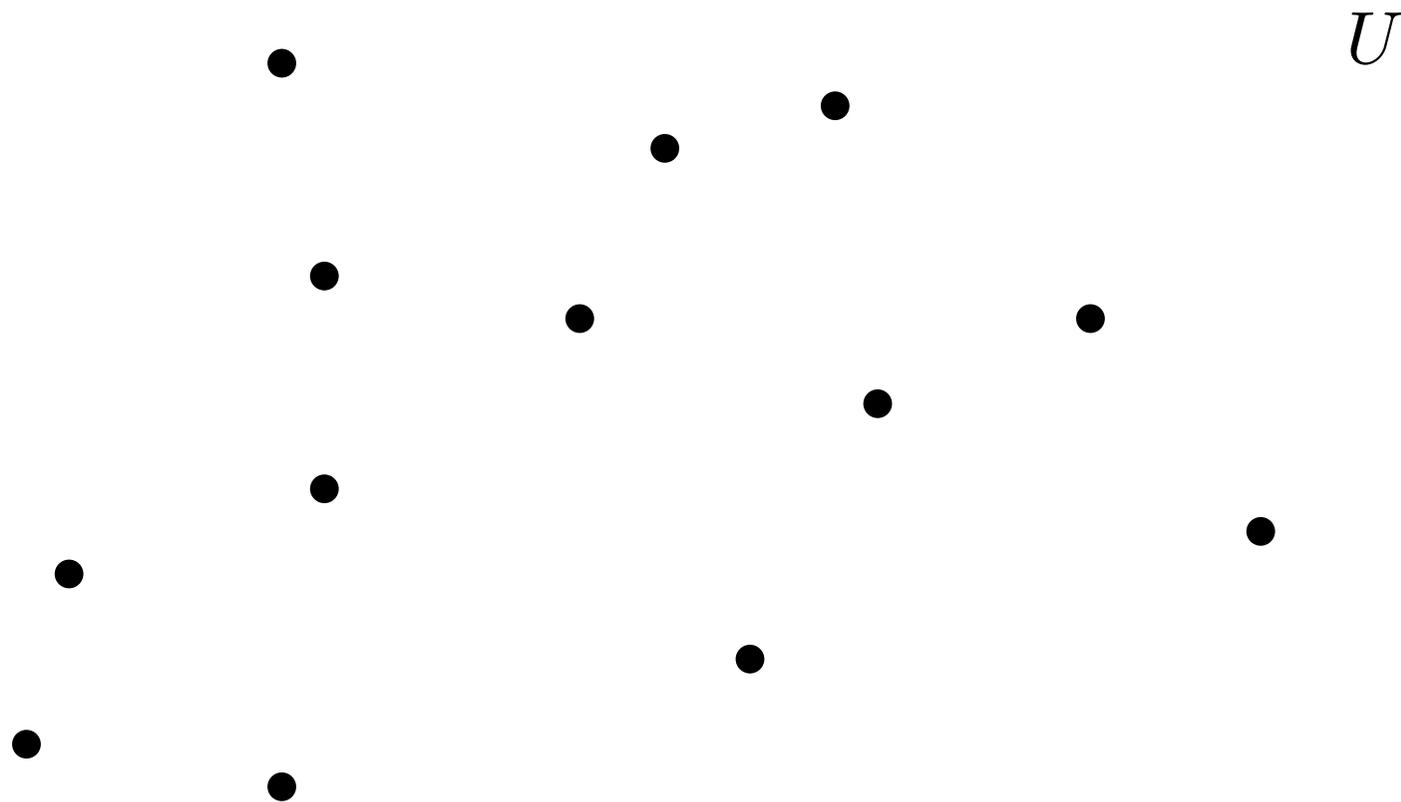
Joint work with Steven Chaplick, Alexander Ravsky, and
Joachim Spoerhase

Maximum Coverage

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, and a positive integer k , find a family $\mathcal{S} \subseteq \mathcal{F}$ of k sets maximizing the number $|\bigcup \mathcal{S}|$ of covered elements.

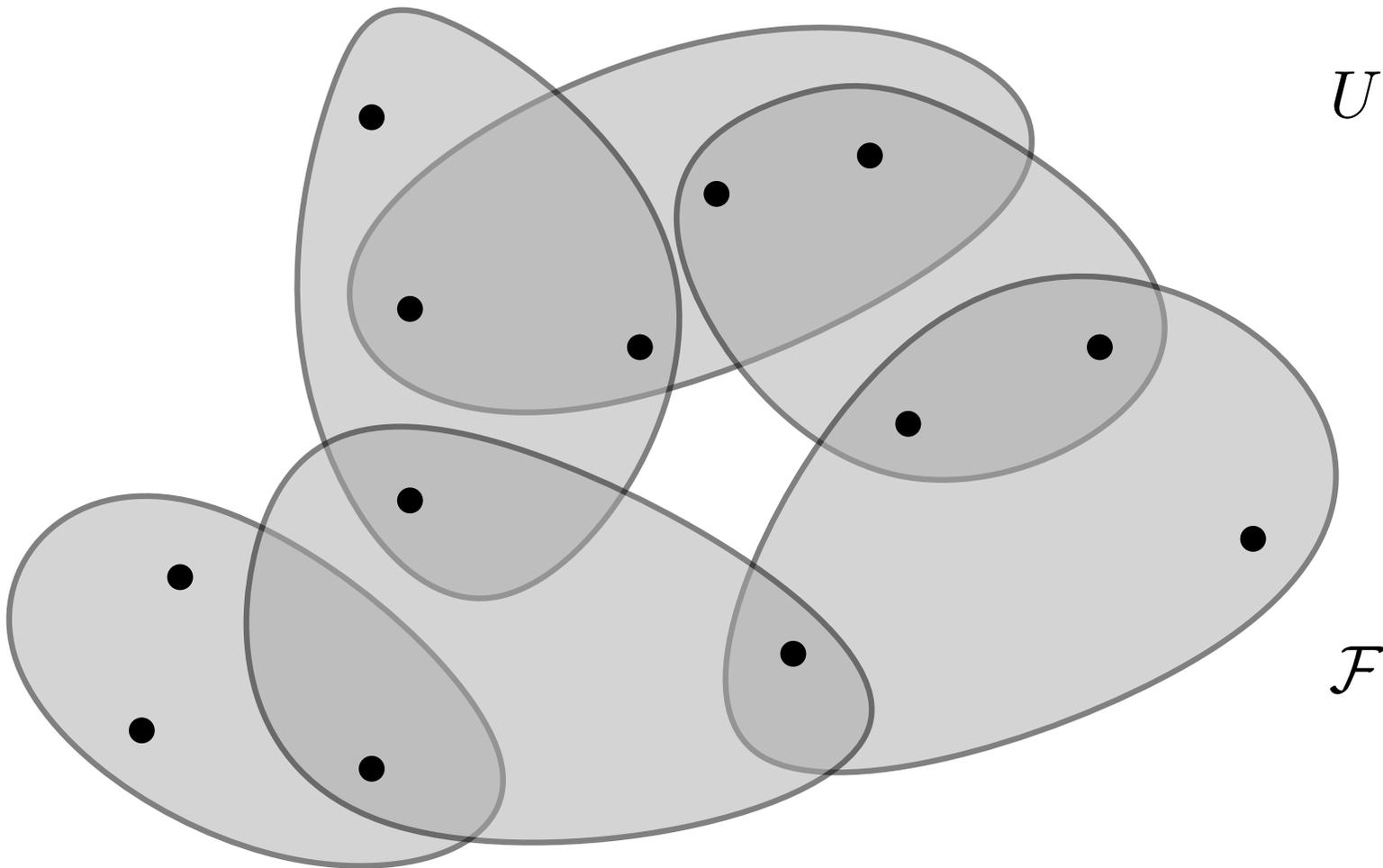
Maximum Coverage

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, and a positive integer k , find a family $\mathcal{S} \subseteq \mathcal{F}$ of k sets maximizing the number $|\bigcup \mathcal{S}|$ of covered elements.



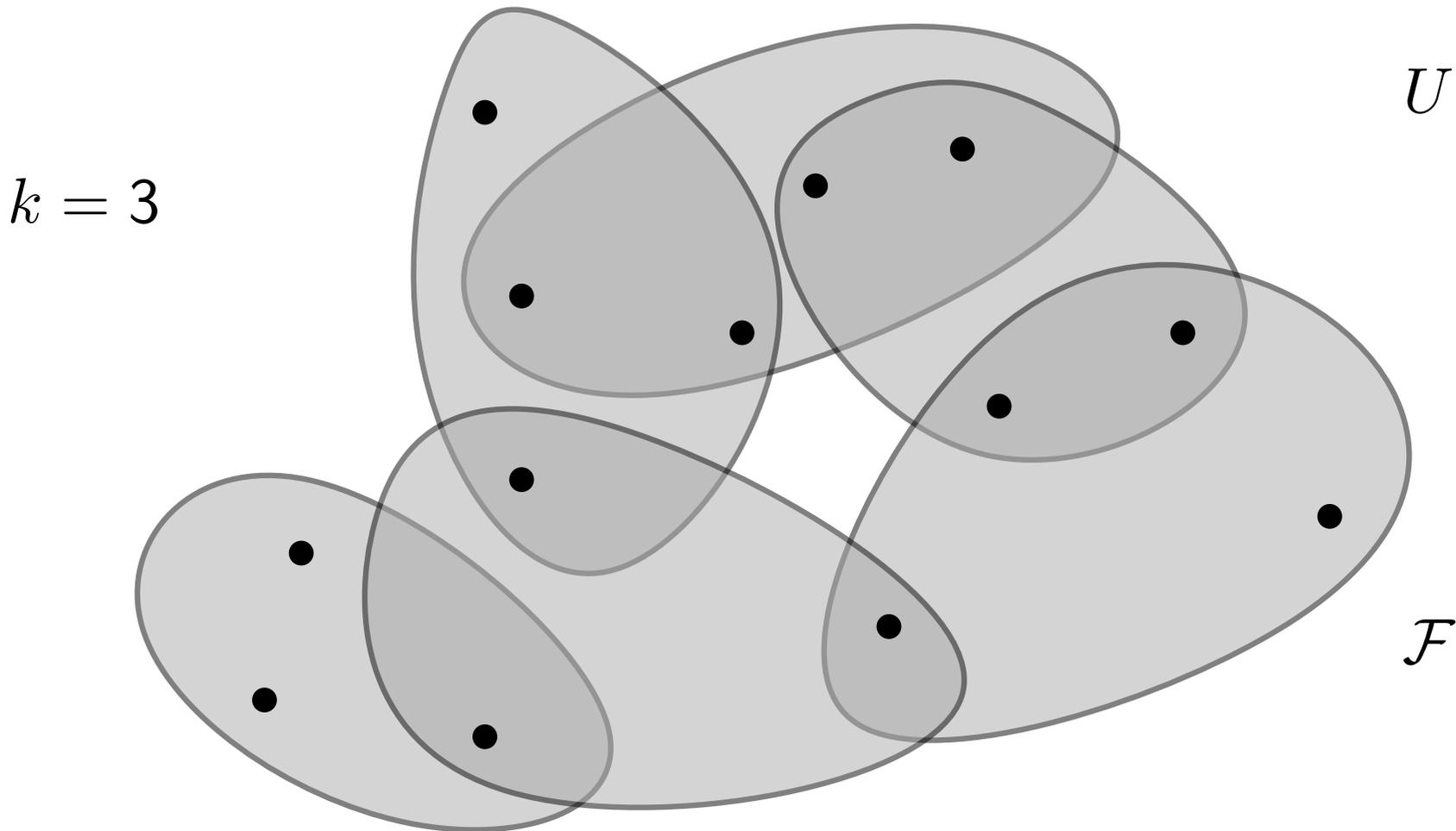
Maximum Coverage

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, and a positive integer k , find a family $\mathcal{S} \subseteq \mathcal{F}$ of k sets maximizing the number $|\bigcup \mathcal{S}|$ of covered elements.



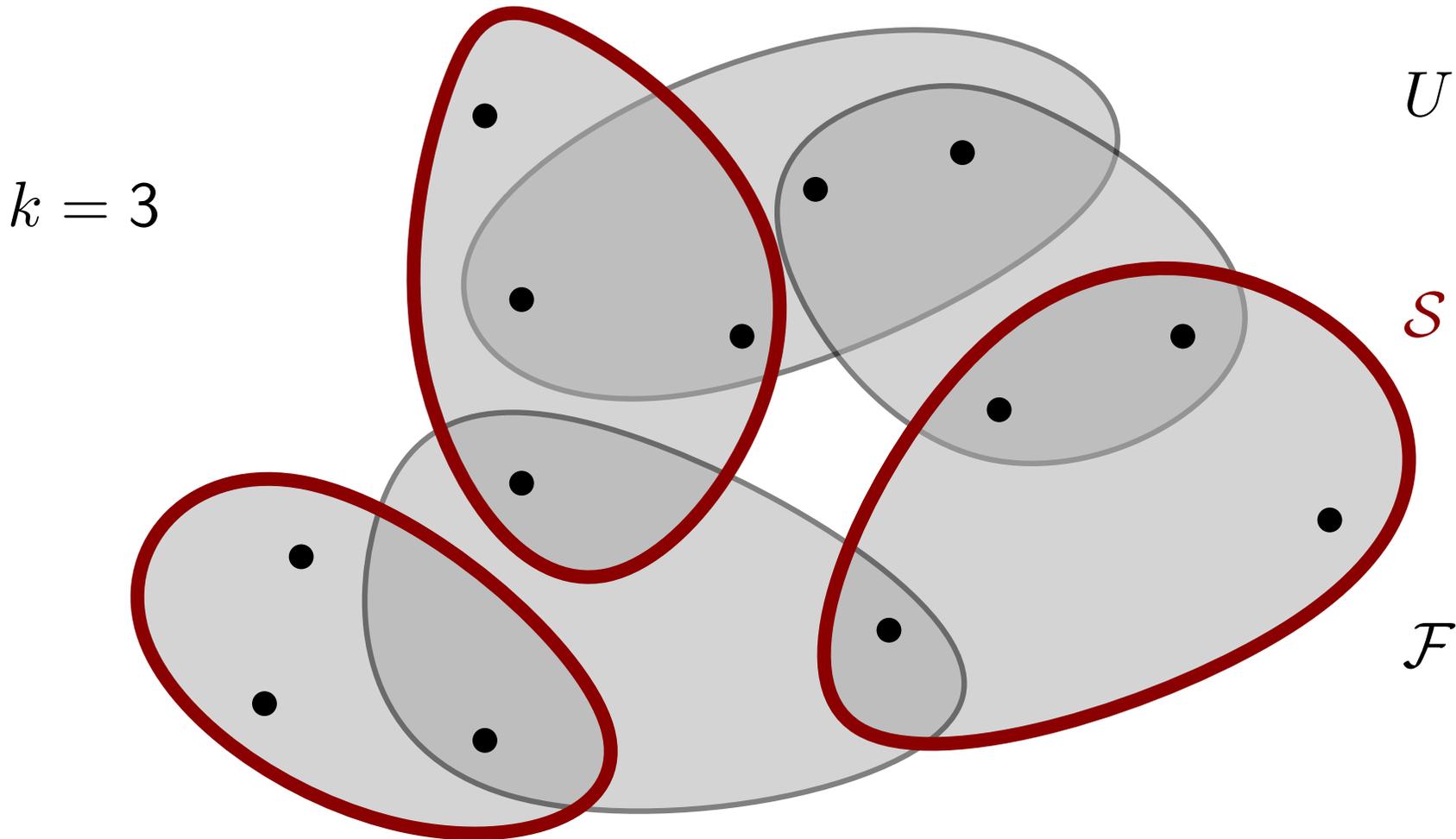
Maximum Coverage

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, and a positive integer k , find a family $\mathcal{S} \subseteq \mathcal{F}$ of k sets maximizing the number $|\bigcup \mathcal{S}|$ of covered elements.



Maximum Coverage

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, and a positive integer k , find a family $\mathcal{S} \subseteq \mathcal{F}$ of k sets maximizing the number $|\bigcup \mathcal{S}|$ of covered elements.



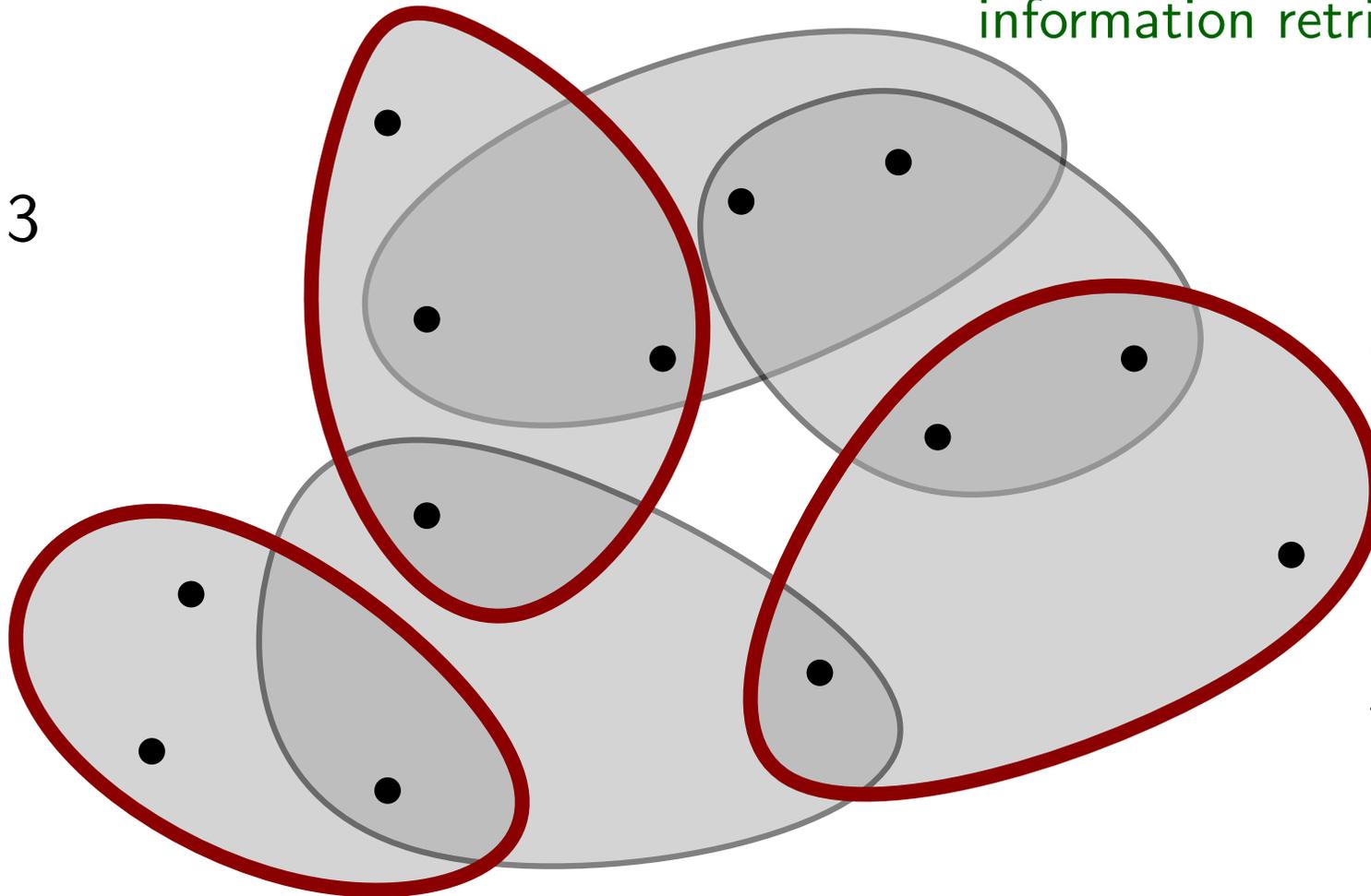
Maximum Coverage

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, and a positive integer k , find a family $\mathcal{S} \subseteq \mathcal{F}$ of k sets maximizing the number $|\bigcup \mathcal{S}|$ of covered elements.

Think of k -document search in information retrieval!

$U \hat{=} \text{users}$

$k = 3$



\mathcal{S}

$\mathcal{F} \hat{=} \text{docs}$

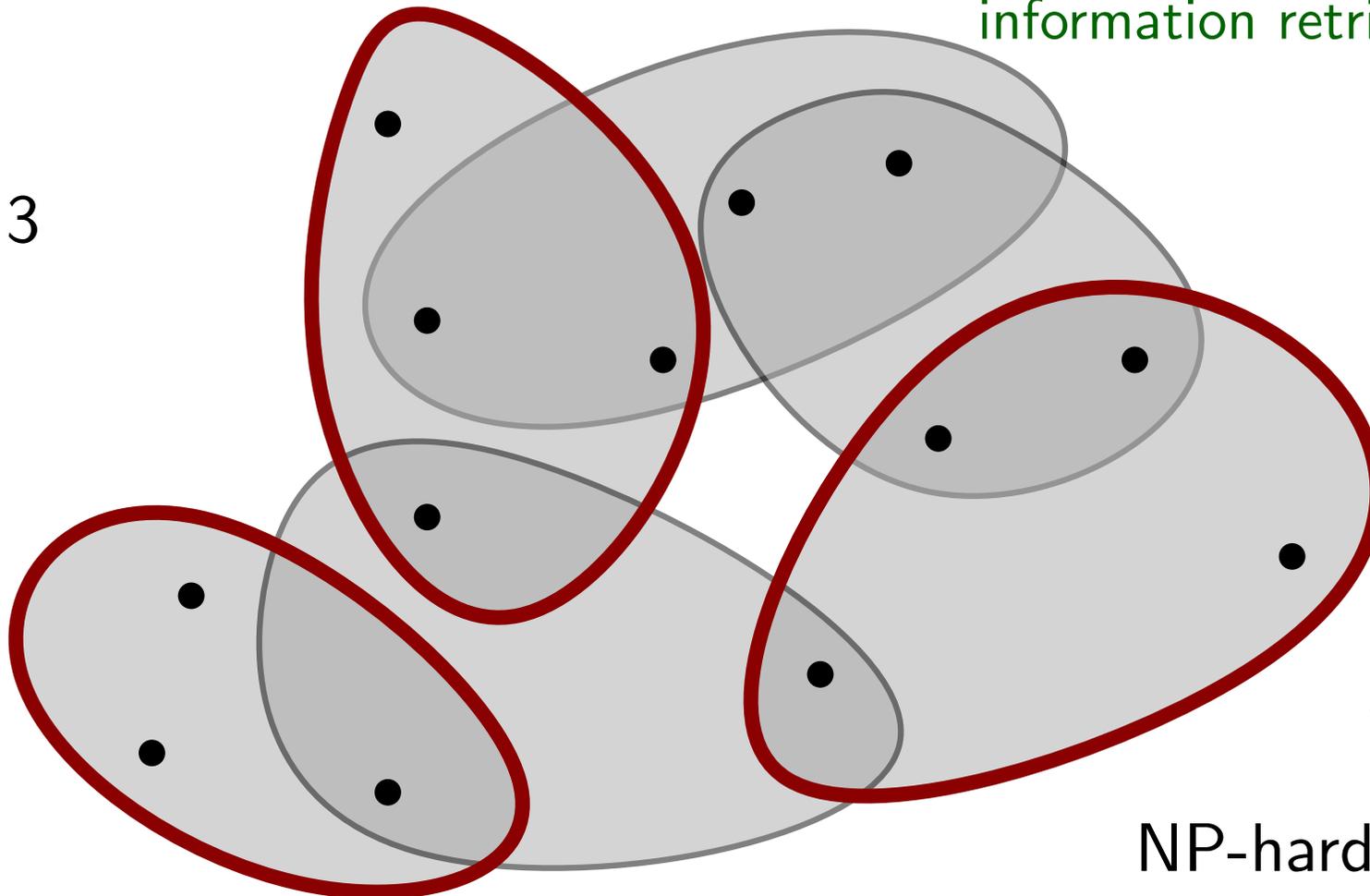
Maximum Coverage

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, and a positive integer k , find a family $\mathcal{S} \subseteq \mathcal{F}$ of k sets maximizing the number $|\bigcup \mathcal{S}|$ of covered elements.

Think of k -document search in information retrieval!

$U \hat{=} \text{users}$

$k = 3$



\mathcal{S}

$\mathcal{F} \hat{=} \text{docs}$

NP-hard

Prior Work and Open Question

General Coverage

Prior Work and Open Question

General Coverage

- greedy gives a $(1 - 1/e)$ -approximation
[Cornuéjols, Nemhauser, Wolsey 1980]
- NP-hard to approximate within $1 - 1/e + \epsilon$ for any $\epsilon > 0$
[Feige 1998]

Prior Work and Open Question

General Coverage

- greedy gives a $(1 - 1/e)$ -approximation
[Cornuéjols, Nemhauser, Wolsey 1980]
- NP-hard to approximate within $1 - 1/e + \epsilon$ for any $\epsilon > 0$
[Feige 1998]

Geometric Coverage

- *parameterized* $(1 - \epsilon)$ -approximation in $f(k, \epsilon) \cdot \text{poly}(n)$ time for set systems with bounded VC-dimension

[Badanidiyuru, Kleinberg, Lee 2012]

Prior Work and Open Question

General Coverage

- greedy gives a $(1 - 1/e)$ -approximation
[Cornuéjols, Nemhauser, Wolsey 1980]
- NP-hard to approximate within $1 - 1/e + \epsilon$ for any $\epsilon > 0$
[Feige 1998]

Geometric Coverage

- *parameterized* $(1 - \epsilon)$ -approximation in $f(k, \epsilon) \cdot \text{poly}(n)$ time for set systems with bounded VC-dimension
- exponential dependence on k cannot be removed as some cases (such as halfspaces in \mathbb{R}^4) are APX-hard
[Badanidiyuru, Kleinberg, Lee 2012]

Prior Work and Open Question

General Coverage

- greedy gives a $(1 - 1/e)$ -approximation
[Cornuéjols, Nemhauser, Wolsey 1980]
- NP-hard to approximate within $1 - 1/e + \epsilon$ for any $\epsilon > 0$
[Feige 1998]

Geometric Coverage

- *parameterized* $(1 - \epsilon)$ -approximation in $f(k, \epsilon) \cdot \text{poly}(n)$ time for set systems with bounded VC-dimension
- exponential dependence on k cannot be removed as some cases (such as halfspaces in \mathbb{R}^4) are APX-hard
[Badanidiyuru, Kleinberg, Lee 2012]

Question: In which of the geometric cases that are not known to be APX-hard (e.g. halfspaces in \mathbb{R}^3 , pseudodisks in \mathbb{R}^2 , ...) can we obtain a (true) PTAS?

Set Cover

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, find a **smallest** family $\mathcal{S} \subseteq \mathcal{F}$ covering the **whole ground set** U

Set Cover

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, find a **smallest** family $\mathcal{S} \subseteq \mathcal{F}$ covering the **whole ground set** U

General Set Cover

- In n -approximation via greedy [Chvátal 1979]
- NP-hard to approximate within $(1 - \epsilon) \ln n$
[Feige 1998, Dinur and Steurer 2014]

Set Cover

Given a ground set U , a set family $\mathcal{F} \subseteq 2^U$, find a **smallest** family $\mathcal{S} \subseteq \mathcal{F}$ covering the **whole ground set** U

General Set Cover

- In n -approximation via greedy [Chvátal 1979]
- NP-hard to approximate within $(1 - \epsilon) \ln n$
[Feige 1998, Dinur and Steurer 2014]

Geometric Set Cover

- many techniques and a large body of literature: ϵ -nets, quasi-uniform sampling and many more ...
- **local search** gives a PTAS for a multitude of problems: halfspaces in \mathbb{R}^3 , pseudodisks in \mathbb{R}^2 , terrain guarding, ...
[Mustafa & Ray 2009]

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$
- start with an arbitrary feasible solution

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$
- start with an arbitrary feasible solution
- repeatedly replace b sets with $< b$ sets as long as possible

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$
- start with an arbitrary feasible solution
- repeatedly replace b sets with $< b$ sets as long as possible

Analysis

- construct an **exchange graph** whose vertices are the sets in a global and a local optimum solution, respectively

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$
- start with an arbitrary feasible solution
- repeatedly replace b sets with $< b$ sets as long as possible

Analysis

- construct an **exchange graph** whose vertices are the sets in a global and a local optimum solution, respectively
- Show that this graph is planar

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$
- start with an arbitrary feasible solution
- repeatedly replace b sets with $< b$ sets as long as possible

Analysis

- construct an **exchange graph** whose vertices are the sets in a global and a local optimum solution, respectively
- Show that this graph is planar
- apply Frederickson's planar subdivision where pieces correspond to candidate swaps

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$
- start with an arbitrary feasible solution
- repeatedly replace b sets with $< b$ sets as long as possible

Analysis

- construct an **exchange graph** whose vertices are the sets in a global and a local optimum solution, respectively
- Show that this graph is planar
- apply Frederickson's planar subdivision where pieces correspond to candidate swaps
- use an averaging argument to show existence of a profitable swap if local \gg global

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$
- start with an arbitrary feasible solution
- repeatedly replace b sets with $< b$ sets as long as possible

Analysis

- construct an **exchange graph** whose vertices are the sets in a global and a local optimum solution, respectively
- Show that this graph is planar **problem-specific part!**
- apply Frederickson's planar subdivision where pieces correspond to candidate swaps
- use an averaging argument to show existence of a profitable swap if local \gg global

Geometric Set Cover and Local Search

[Mustafa & Ray 2009]

Algorithm

- pick an integral parameter $b > 0$
- start with an arbitrary feasible solution
- repeatedly replace b sets with $< b$ sets as long as possible

Analysis

- construct an **exchange graph** whose vertices are the sets in a global and a local optimum solution, respectively
- Show that this graph is planar
- apply Frederickson's planar subdivision where pieces correspond to candidate swaps **general machinery!**
- use an averaging argument to show existence of a profitable swap if local \gg global

Machinery Applicable to Geometric Coverage?

Problem	Set Cover	Max Coverage
halfspaces in \mathbb{R}^3	PTAS via LS [Mustafa, Ray 2009]	PTAS via LS conjectured! [Badanidiyuru, Kleinberg, Lee 2012]

Machinery Applicable to Geometric Coverage?

Problem	Set Cover	Max Coverage
halfspaces in \mathbb{R}^3	PTAS via LS [Mustafa, Ray 2009]	PTAS via LS conjectured! [Badanidiyuru, Kleinberg, Lee 2012]
halfspaces in \mathbb{R}^2	in P via DP [Har-Peled, Lee 2008]	P via DP [Har-Peled, Lee 2008] [Badanidiyuru, Kleinberg, Lee 2012]
pseudodisks	PTAS via LS	open

Machinery Applicable to Geometric Coverage?

Problem	Set Cover	Max Coverage
halfspaces in \mathbb{R}^3	PTAS via LS [Mustafa, Ray 2009]	PTAS via LS conjectured! [Badanidiyuru, Kleinberg, Lee 2012]
halfspaces in \mathbb{R}^2	in P via DP [Har-Peled, Lee 2008]	P via DP [Har-Peled, Lee 2008] [Badanidiyuru, Kleinberg, Lee 2012]
pseudodisks	PTAS via LS [Pyrga, Ray 2008]	open
hitting pseudodisks	PTAS via LS [Pyrga, Ray 2008]	open
1.5D terrain guarding	PTAS via LS [Krohn et al. 2014]	open
⋮	⋮	⋮

Machinery Applicable to Geometric Coverage?

Problem	Set Cover	Max Coverage
halfspaces in \mathbb{R}^3	PTAS via LS [Mustafa, Ray 2009]	PTAS via LS conjectured! [Badanidiyuru, Kleinberg, Lee 2012]
halfspaces in \mathbb{R}^2	in P via DP [Har-Peled, Lee 2008]	P via DP [Har-Peled, Lee 2008] [Badanidiyuru, Kleinberg, Lee 2012]
pseudodisks	PTAS via LS [Pyrga, Ray 2008]	open
hitting pseudodisks	PTAS via LS [Pyrga, Ray 2008]	open
1.5D terrain guarding	PTAS via LS [Krohn et al. 2014]	open
⋮	⋮	⋮

planar exchange graph

Set Cover

PTAS

Machinery Applicable to Geometric Coverage?

Problem	Set Cover	Max Coverage
halfspaces in \mathbb{R}^3	PTAS via LS [Mustafa, Ray 2009]	PTAS via LS conjectured! [Badanidiyuru, Kleinberg, Lee 2012]
halfspaces in \mathbb{R}^2	in P via DP [Har-Peled, Lee 2008]	P via DP [Har-Peled, Lee 2008] [Badanidiyuru, Kleinberg, Lee 2012]
pseudodisks	PTAS via LS [Pyrga, Ray 2008]	open
hitting pseudodisks	PTAS via LS [Pyrga, Ray 2008]	open
1.5D terrain guarding	PTAS via LS [Krohn et al. 2014]	open
⋮	⋮	⋮

planar exchange graph

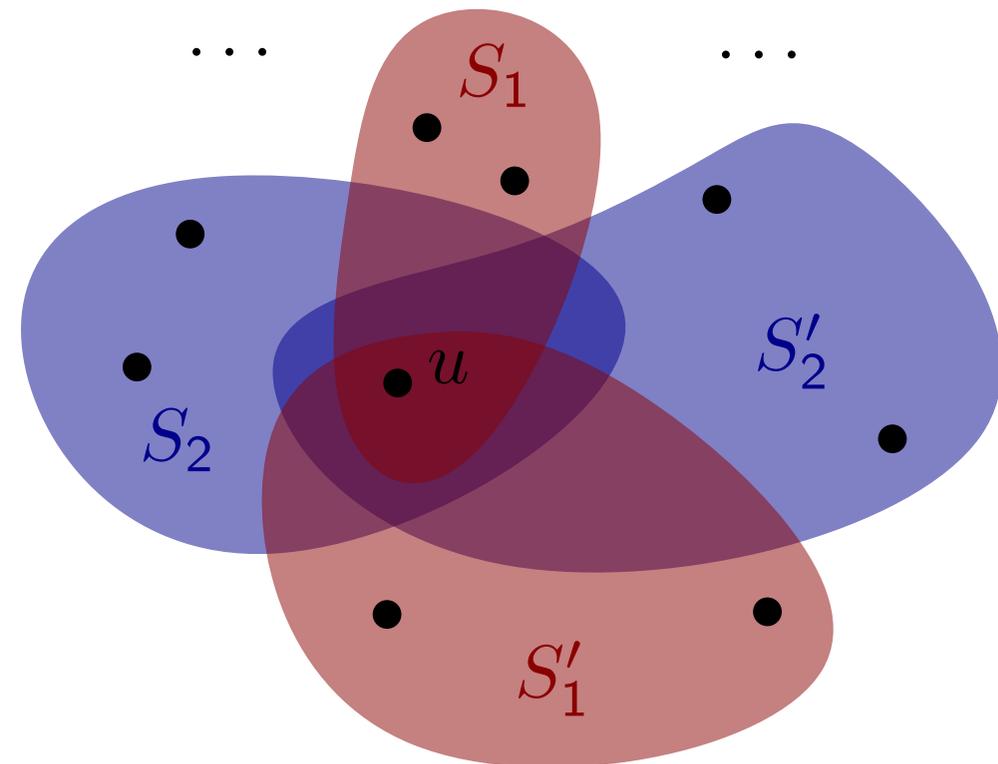
Set Cover
Max Coverage?

PTAS

Exchange Graph

[Mustafa & Ray 2009]

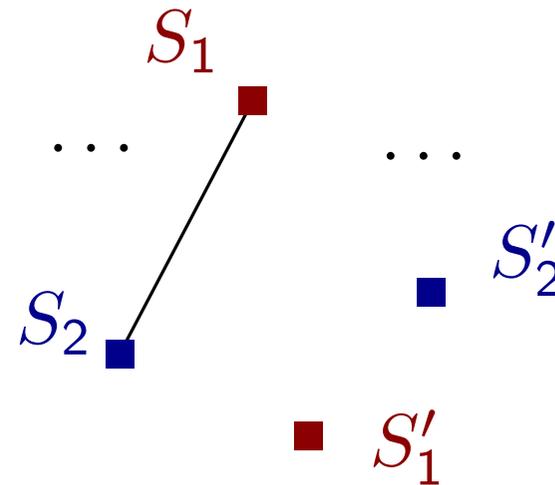
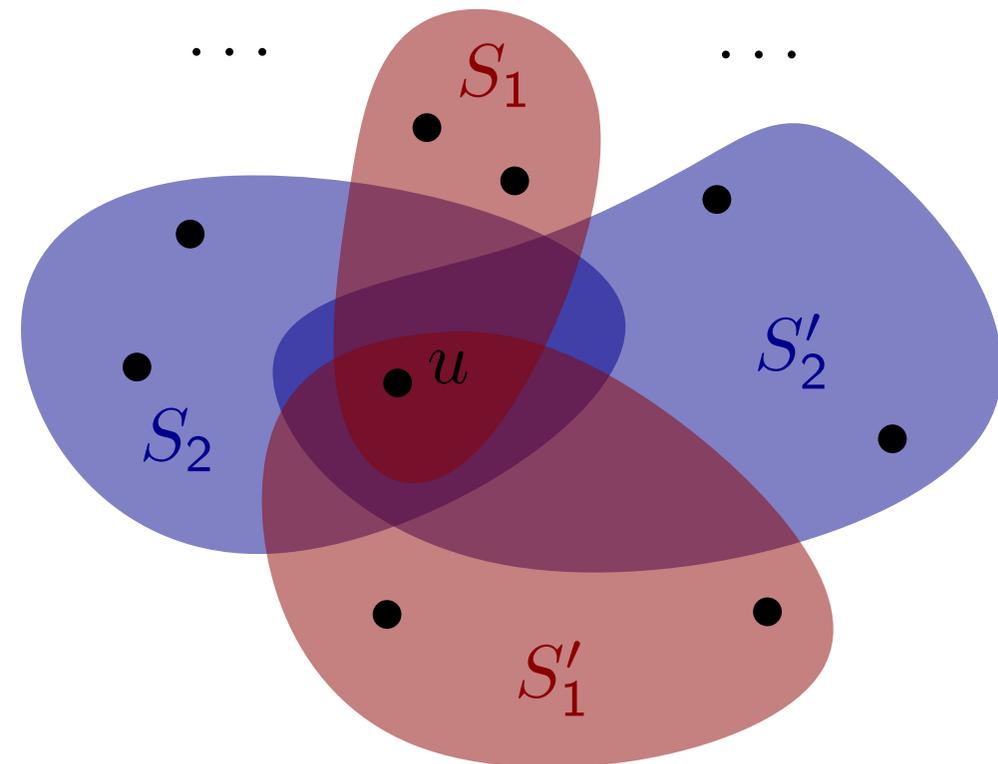
Let $\mathcal{F}_1, \mathcal{F}_2$ be feasible solutions. A graph with node set $\mathcal{F}_1, \mathcal{F}_2$ has the **exchange property** if for every $u \in U$ covered by both solutions there exist an edge (S_1, S_2) with $u \in S_1 \cap S_2$ and $S_i \in \mathcal{F}_i$



Exchange Graph

[Mustafa & Ray 2009]

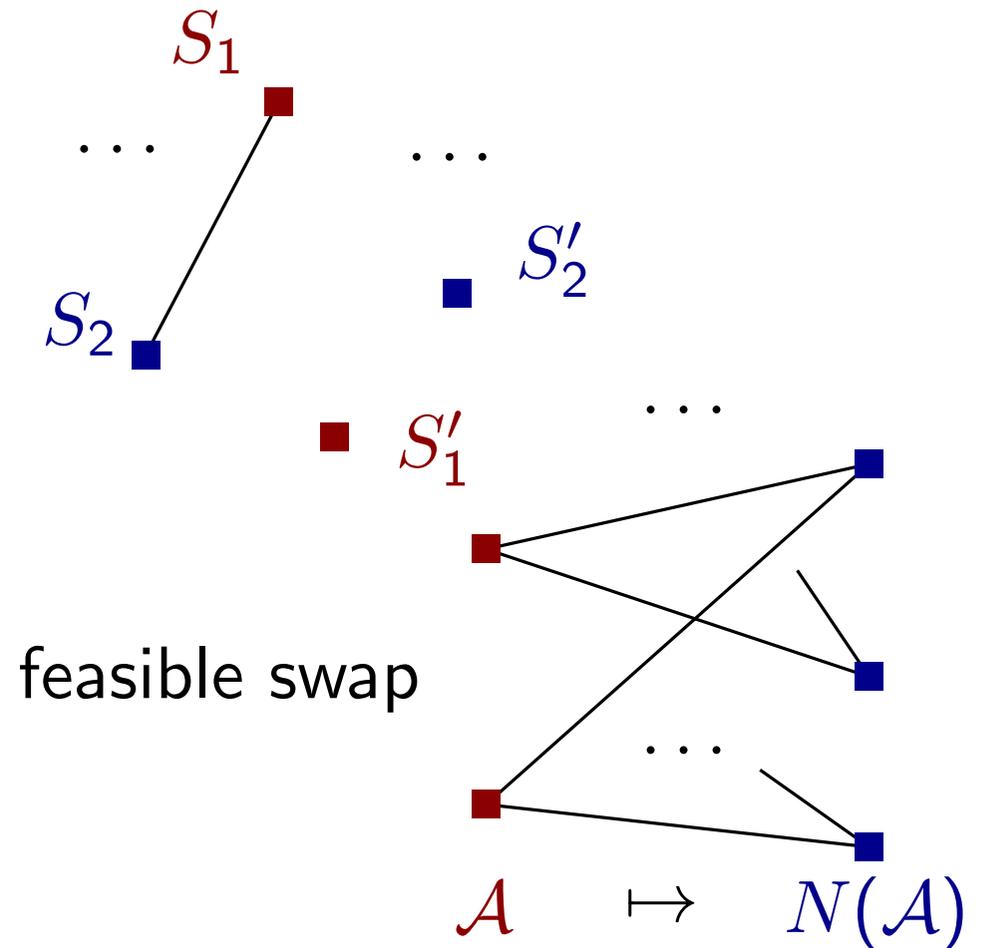
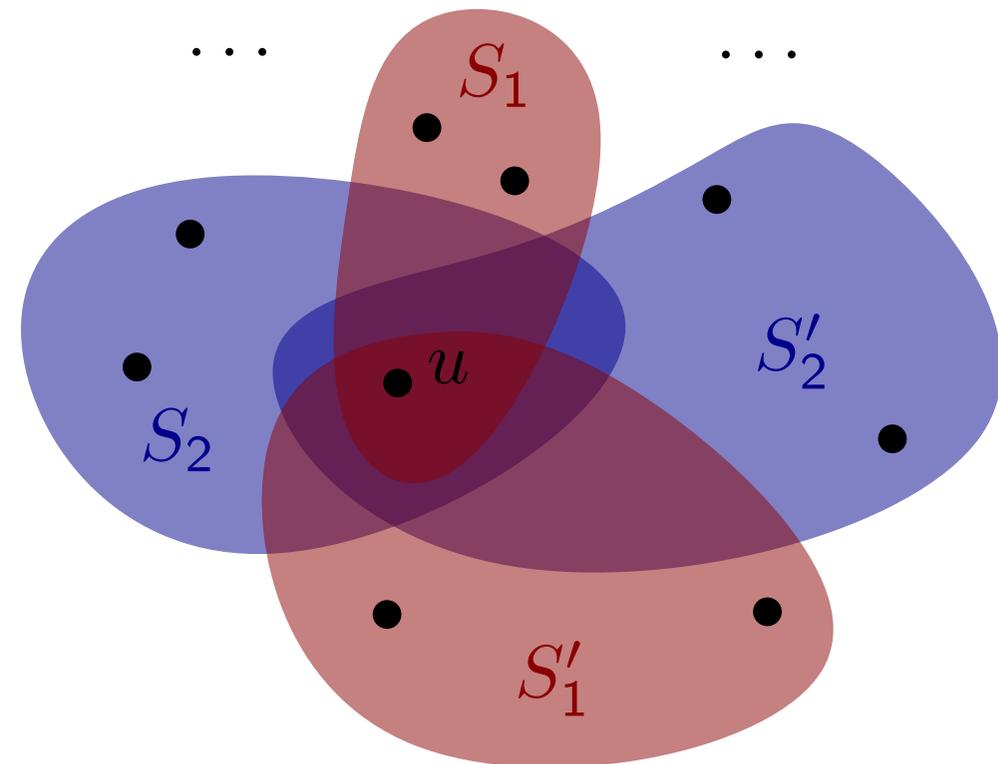
Let $\mathcal{F}_1, \mathcal{F}_2$ be feasible solutions. A graph with node set $\mathcal{F}_1, \mathcal{F}_2$ has the **exchange property** if for every $u \in U$ covered by both solutions there exist an edge (S_1, S_2) with $u \in S_1 \cap S_2$ and $S_i \in \mathcal{F}_i$



Exchange Graph

[Mustafa & Ray 2009]

Let $\mathcal{F}_1, \mathcal{F}_2$ be feasible solutions. A graph with node set $\mathcal{F}_1, \mathcal{F}_2$ has the **exchange property** if for every $u \in U$ covered by both solutions there exist an edge (S_1, S_2) with $u \in S_1 \cap S_2$ and $S_i \in \mathcal{F}_i$



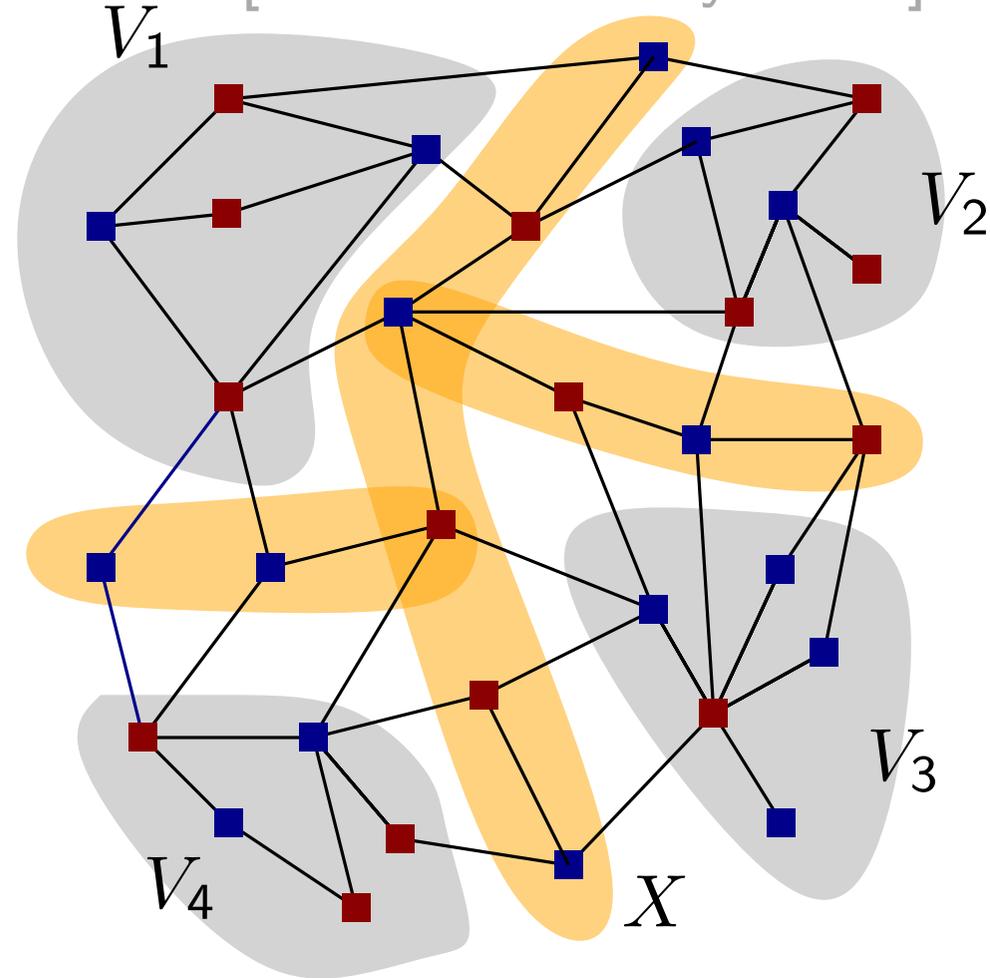
Subdividing Planar Exchange Graphs

[Mustafa & Ray 2009]

Theorem (Frederickson 1987):

For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = O(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(\sqrt{t})$



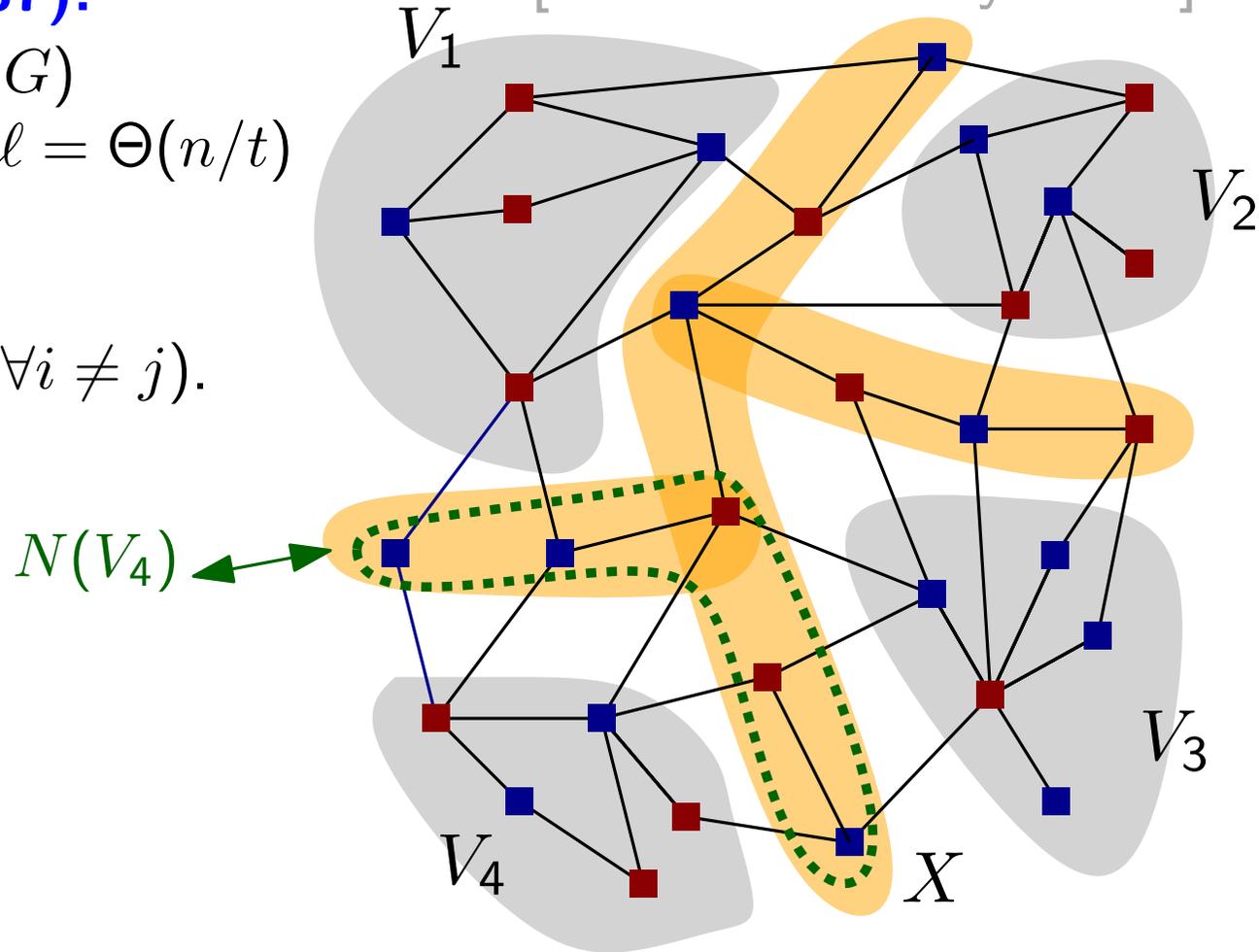
Subdividing Planar Exchange Graphs

[Mustafa & Ray 2009]

Theorem (Frederickson 1987):

For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = O(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(\sqrt{t})$



Subdividing Planar Exchange Graphs

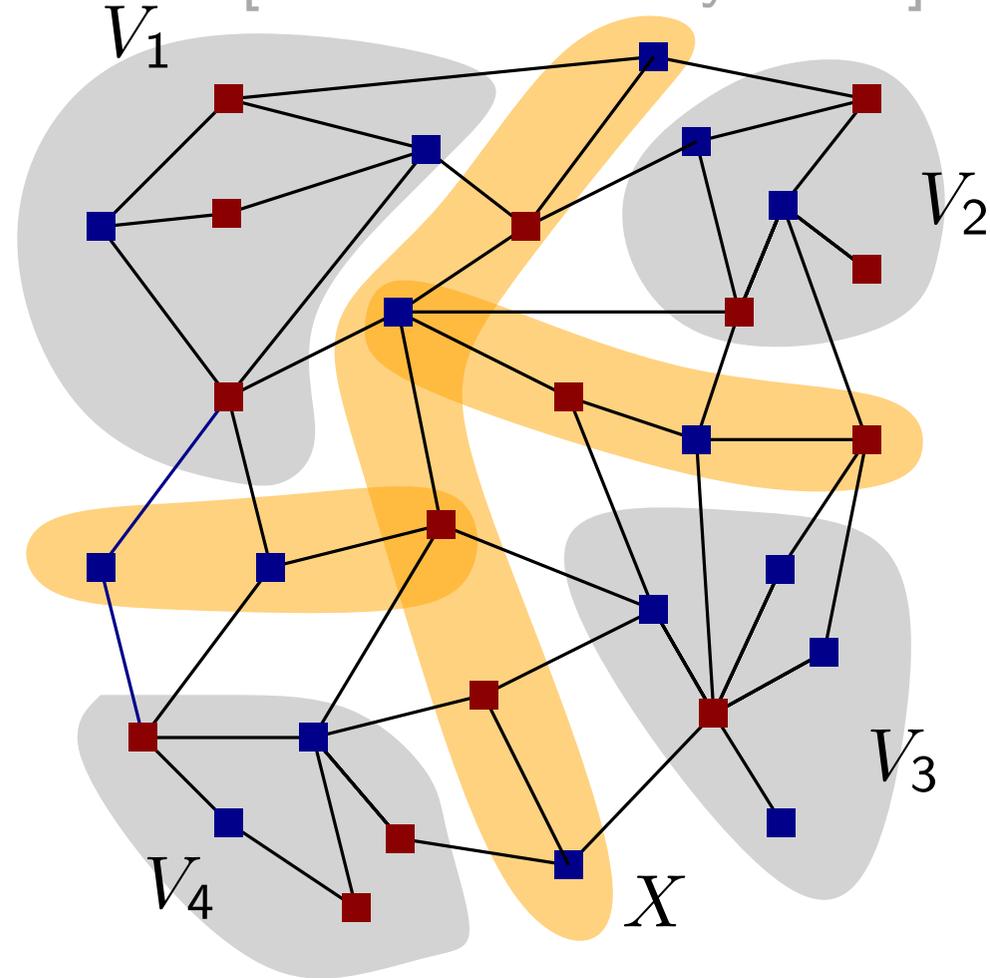
[Mustafa & Ray 2009]

Theorem (Frederickson 1987):

For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = O(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(\sqrt{t})$

Subdivide planar exchange graph over optimal solution \mathcal{O} and locally optimal solution \mathcal{S}



Subdividing Planar Exchange Graphs

[Mustafa & Ray 2009]

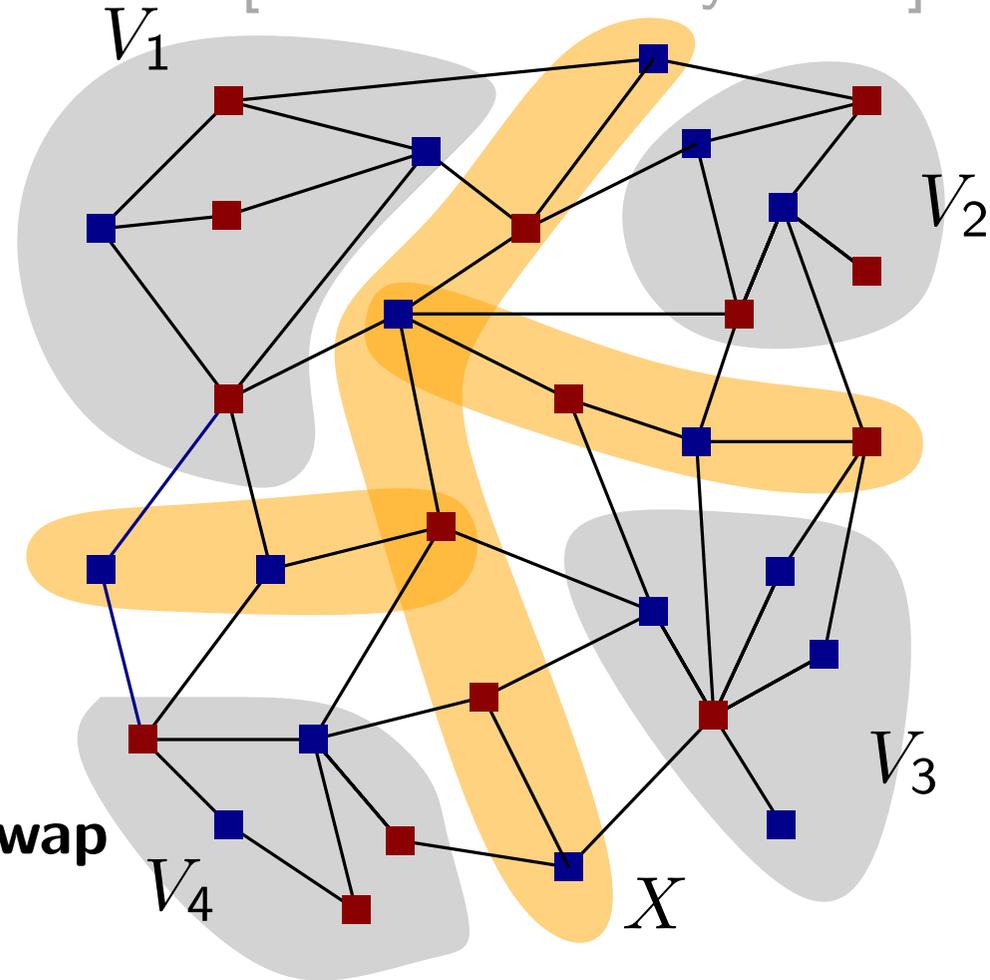
Theorem (Frederickson 1987):

For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = O(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(\sqrt{t})$

Subdivide planar exchange graph over optimal solution \mathcal{O} and locally optimal solution \mathcal{S}

Each $\bar{V}_i = V_i \cup N(V_i)$ defines **feasible swap**
 $V_i \cap \mathcal{S} \mapsto \bar{V}_i \cap \mathcal{O}$ for \mathcal{S}



Subdividing Planar Exchange Graphs

[Mustafa & Ray 2009]

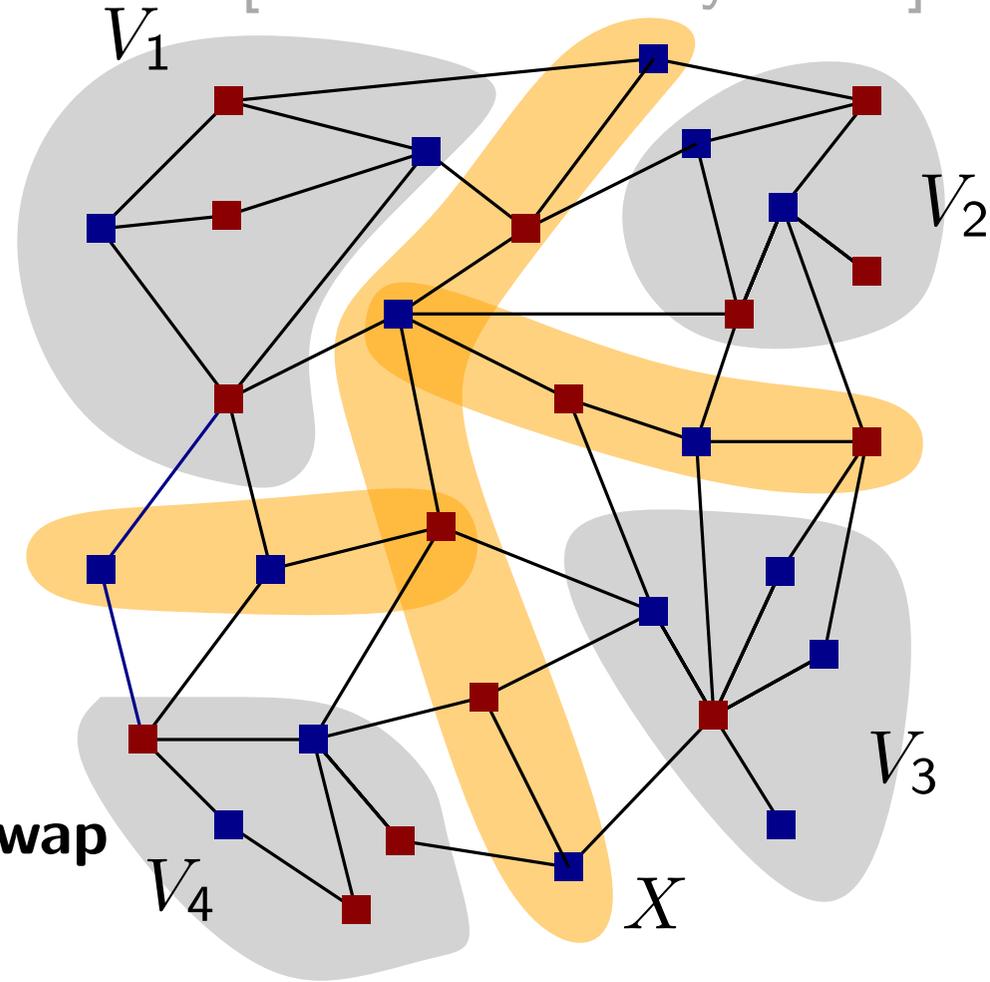
Theorem (Frederickson 1987):

For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = O(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(\sqrt{t})$

Subdivide planar exchange graph over optimal solution \mathcal{O} and locally optimal solution \mathcal{S}

Each $\bar{V}_i = V_i \cup N(V_i)$ defines **feasible swap**
 $V_i \cap \mathcal{S} \mapsto \bar{V}_i \cap \mathcal{O}$ for \mathcal{S}



$$|\mathcal{S}| \leq |X| + \sum_i |V_i \cap \mathcal{S}| \leq |X| + \sum_i |\bar{V}_i \cap \mathcal{O}| \leq \frac{2}{\sqrt{t}}(|\mathcal{S}| + |\text{OPT}|) + |\text{OPT}|$$

Subdividing Planar Exchange Graphs

[Mustafa & Ray 2009]

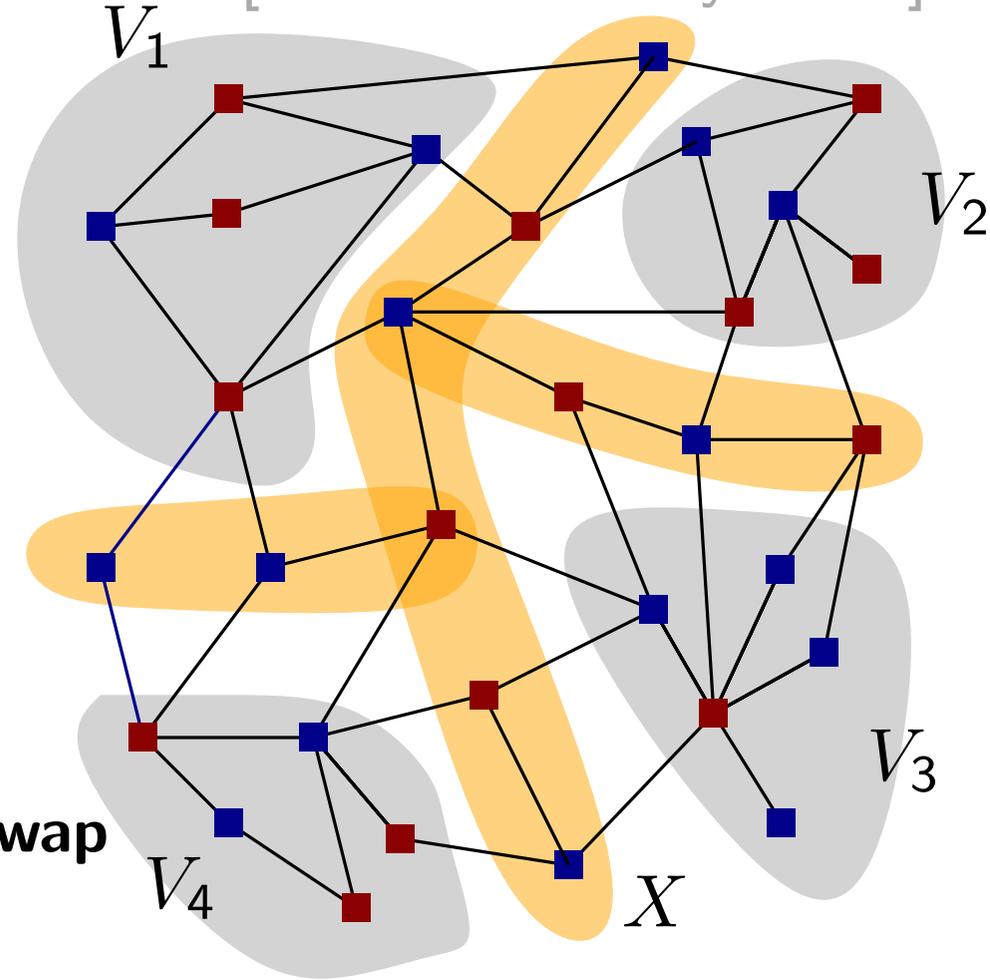
Theorem (Frederickson 1987):

For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = O(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(\sqrt{t})$

Subdivide planar exchange graph over optimal solution \mathcal{O} and locally optimal solution \mathcal{S}

Each $\bar{V}_i = V_i \cup N(V_i)$ defines **feasible swap**
 $V_i \cap \mathcal{S} \mapsto \bar{V}_i \cap \mathcal{O}$ for \mathcal{S}



$$|\mathcal{S}| \leq |X| + \sum_i |V_i \cap \mathcal{S}| \leq |X| + \sum_i |\bar{V}_i \cap \mathcal{O}| \leq \frac{2}{\sqrt{t}} (|\mathcal{S}| + |\text{OPT}|) + |\text{OPT}|$$

$$\rightsquigarrow |\mathcal{S}| \leq \frac{1 + \frac{2}{\sqrt{t}}}{1 - \frac{2}{\sqrt{t}}} |\text{OPT}|$$

Algorithm/Hurdles for Max Coverage

local search: swaps **do not change cardinality** of the solution ^[this work]
but **improve number of covered elements**

Algorithm/Hurdles for Max Coverage

local search: swaps **do not change cardinality** of the solution ^[this work]
but **improve number of covered elements**

Hurdles

1. does exchange graph still reflect the **objective function**?
 - maximization \Leftrightarrow covering is no hard constraint
 - exchange graph takes into account only elements covered by both solution but no individual elements

Algorithm/Hurdles for Max Coverage

local search: swaps **do not change cardinality** of the solution ^[this work]
but **improve number of covered elements**

Hurdles

1. does exchange graph still reflect the **objective function**?
 - maximization \Leftrightarrow covering is no hard constraint
 - exchange graph takes into account only elements covered by both solution but no individual elements
2. color-imbalanced subdivisions conflict with **hard cardinality constraint**

Our Results

Theorem: There is a PTAS for any class of max coverage problems that admits planar (f -separable) exchange graphs.

Our Results

Theorem: There is a PTAS for any class of max coverage problems that admits planar (f -separable) exchange graphs.

Corollary: Max coverage admits a PTAS for

- covering points with halfspaces in \mathbb{R}^3
- covering points with pseudodisks in \mathbb{R}^2
- hitting pseudodisks (r -admissible regions) in \mathbb{R}^2 by points
- guarding 1.5D terrains
- maximum k -dominating set for intersection graphs of homothetic copies of convex objects (such as arbitrary squares, translated and scaled copies of convex objects)
- maximum k -dominating set on non-trivial minor-closed graph classes
- maximum k -vertex cover on f -separable on subgraph-closed graph classes
- ...

Our Results

Theorem: There is a PTAS for any class of max coverage problems that admits planar (f -separable) exchange graphs.

Corollary: Max coverage admits a PTAS for

confirms conjecture by Badanidiyuru, Kleinberg, Lee 2012

- covering points with halfspaces in \mathbb{R}^3
- covering points with pseudodisks in \mathbb{R}^2
- hitting pseudodisks (r -admissible regions) in \mathbb{R}^2 by points
- guarding 1.5D terrains
- maximum k -dominating set for intersection graphs of homothetic copies of convex objects (such as arbitrary squares, translated and scaled copies of convex objects)
- maximum k -dominating set on non-trivial minor-closed graph classes
- maximum k -vertex cover on f -separable on subgraph-closed graph classes
- ...

High-Level Overview

[this work]

1. Get a nearly color-balanced subdivision

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(t^{3/4})$, $\forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t})$, $\forall i$

High-Level Overview

[this work]

1. Get a nearly color-balanced subdivision

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(t^{3/4})$, $\forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t})$, $\forall i$

High-Level Overview

[this work]

1. Get a **nearly color-balanced subdivision**

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(t^{3/4})$, $\forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t})$, $\forall i$

2. Obtain a **significantly profitable, almost balanced swap**

High-Level Overview

[this work]

1. Get a **nearly color-balanced subdivision**

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t)$, $\forall i$.
- X separates V_i from V_j , ($\forall i \neq j$).
- $|N(V_i)| = O(t^{3/4})$, $\forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t})$, $\forall i$

2. Obtain a **significantly profitable, almost balanced swap**

3. Use **submodularity** to get a **perfectly balanced** and (still) **profitable swap**

Obtaining Approximate Color-Balance

[this work]

Step 1.1: **Uniform** subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$

Obtaining Approximate Color-Balance

[this work]

Step 1.1: **Uniform** subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$

- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$
- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(t^{3/4}), \forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$

Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from V_j , $(\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$

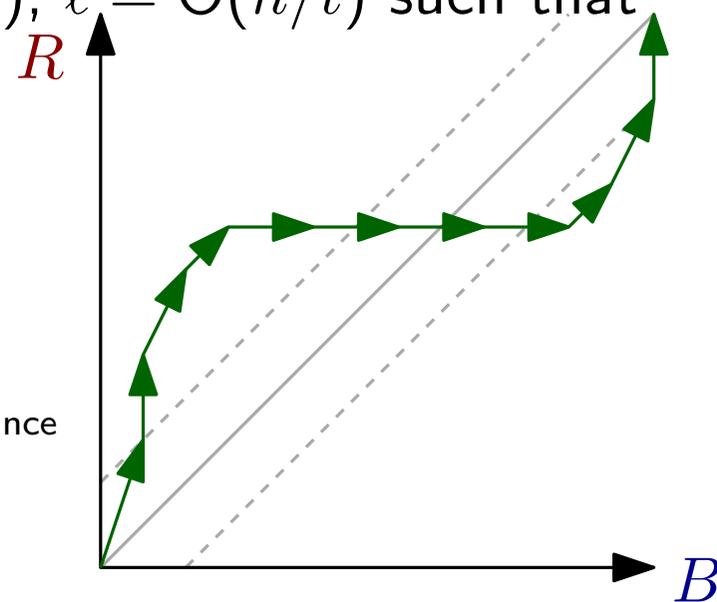
- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from V_j , $(\forall i \neq j).$
- $|N(V_i)| = O(t^{3/4}), \forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$

- compute **uniform** subdivision with $t' = \sqrt{t}$
- greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
- break π into $\Theta(n/t)$ equal-sized intervals
- yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

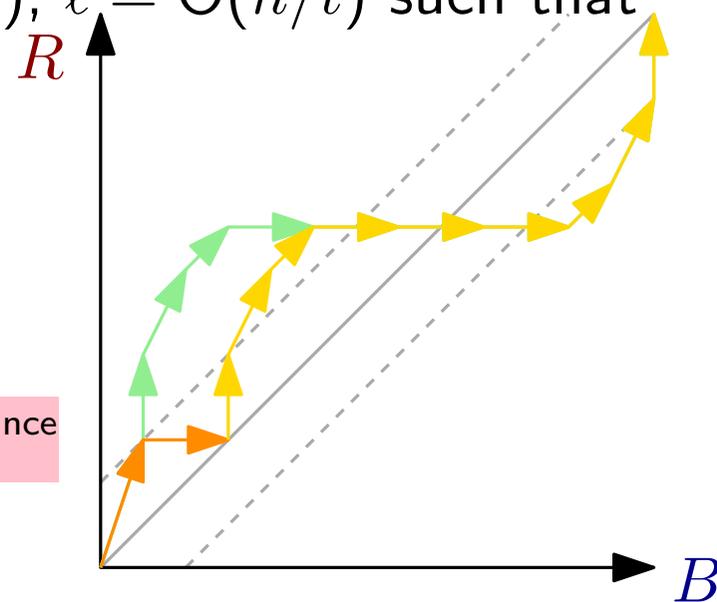
Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$
- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(t^{3/4}), \forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$
- compute **uniform** subdivision with $t' = \sqrt{t}$
- greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
- break π into $\Theta(n/t)$ equal-sized intervals
- yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$

- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

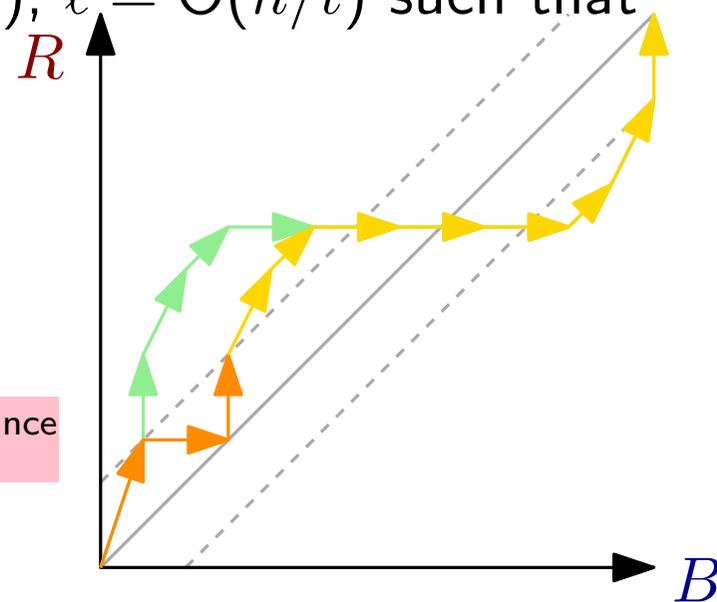
Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$

- $|N(V_i)| = O(t^{3/4}), \forall i$

- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$

- compute **uniform** subdivision with $t' = \sqrt{t}$
- greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
- break π into $\Theta(n/t)$ equal-sized intervals
- yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

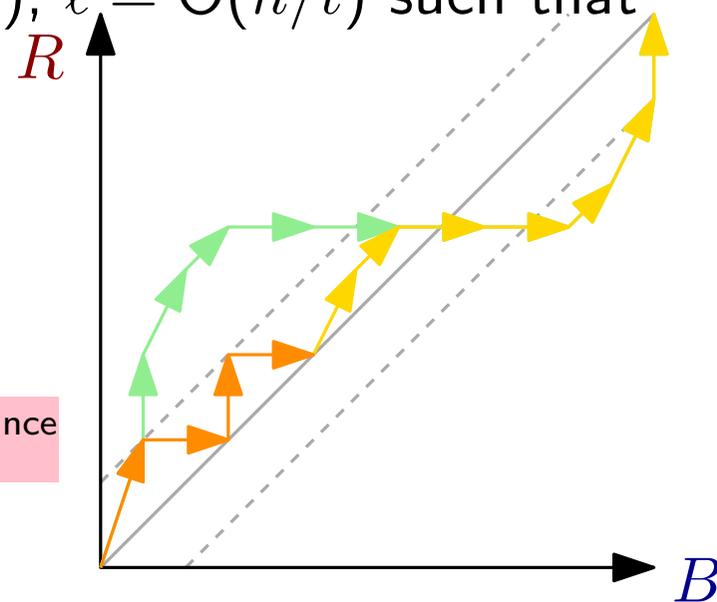
Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$
- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(t^{3/4}), \forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$
- compute **uniform** subdivision with $t' = \sqrt{t}$
- greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
- break π into $\Theta(n/t)$ equal-sized intervals
- yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$

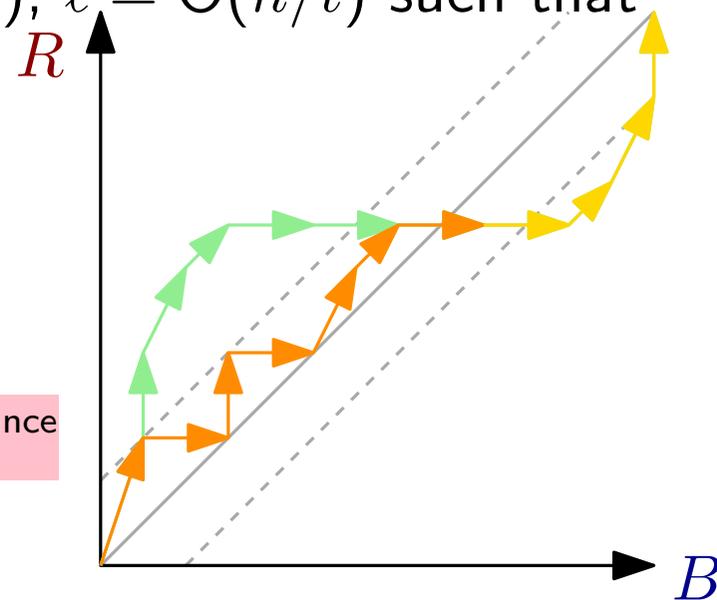
- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(t^{3/4}), \forall i$
- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$

- compute **uniform** subdivision with $t' = \sqrt{t}$
- greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
- break π into $\Theta(n/t)$ equal-sized intervals
- yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$

- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

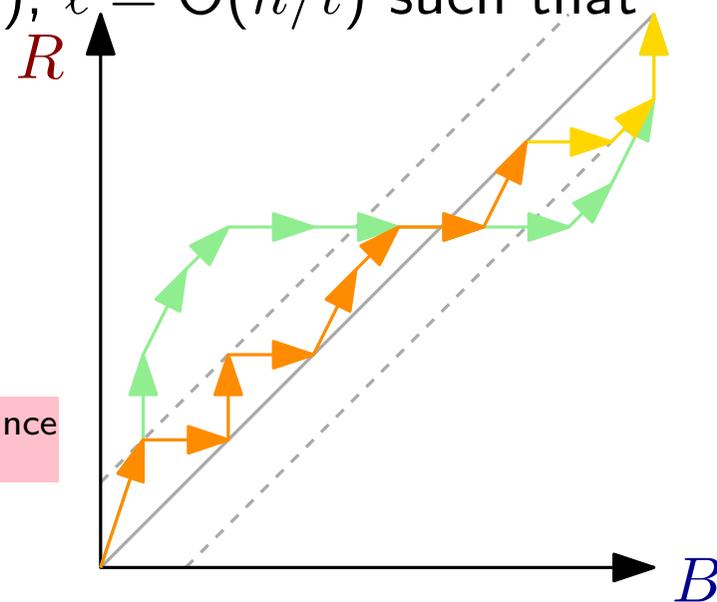
Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$

- $|N(V_i)| = O(t^{3/4}), \forall i$

- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$

- compute **uniform** subdivision with $t' = \sqrt{t}$
- greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
- break π into $\Theta(n/t)$ equal-sized intervals
- yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

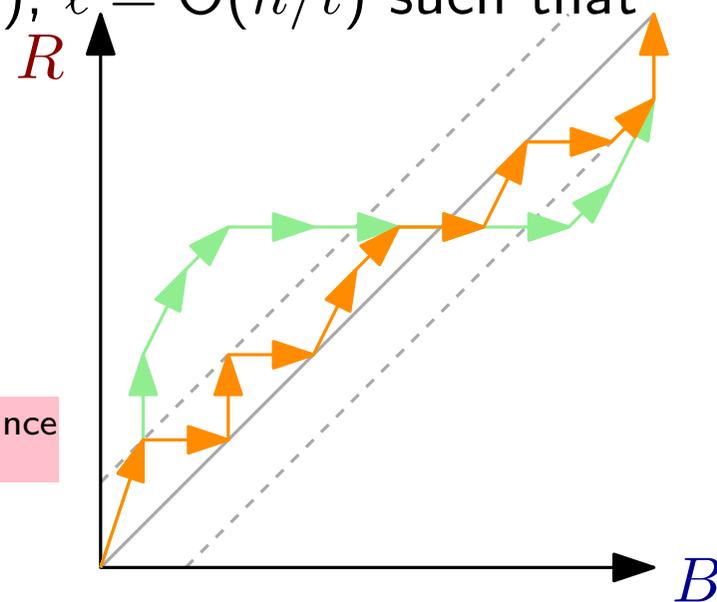
Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
 - X separates V_i from $V_j, (\forall i \neq j).$
 - $|N(V_i)| = O(\sqrt{t}), \forall i$
- start with (non-uniform) Frederickson subdivision
 - group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
 - bin packing type of argument

Step 1.2: Approximate color balance

Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
 - X separates V_i from $V_j, (\forall i \neq j).$
 - $|N(V_i)| = O(t^{3/4}), \forall i$
 - $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$
- compute **uniform** subdivision with $t' = \sqrt{t}$
 - greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
 - break π into $\Theta(n/t)$ equal-sized intervals
 - yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$

- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

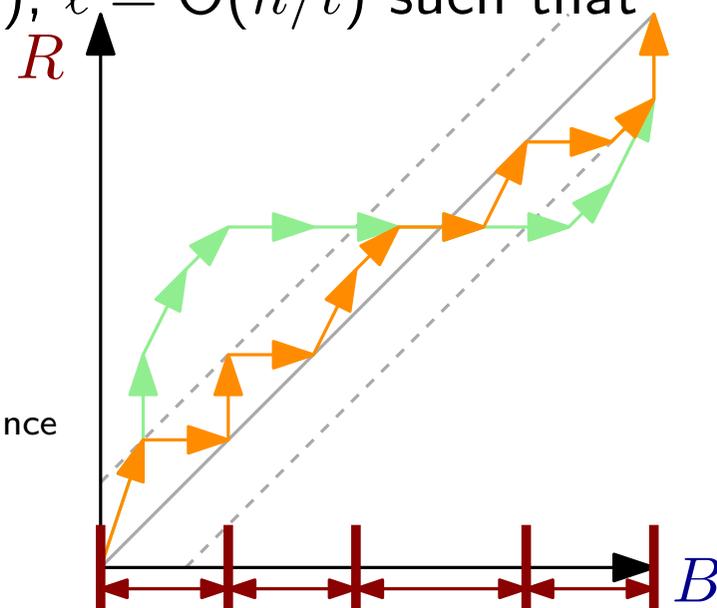
Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$

- $|N(V_i)| = O(t^{3/4}), \forall i$

- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$

- compute **uniform** subdivision with $t' = \sqrt{t}$
- greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
- break π into $\Theta(n/t)$ equal-sized intervals
- yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



Obtaining Approximate Color-Balance

[this work]

Step 1.1: Uniform subdivision

Lemma: For every $t > 0$, planar G , $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$
- $|N(V_i)| = O(\sqrt{t}), \forall i$

- start with (non-uniform) Frederickson subdivision
- group small (and big) pieces guaranteeing the lower bound while preserving an upper bound on their boundary
- bin packing type of argument

Step 1.2: Approximate color balance

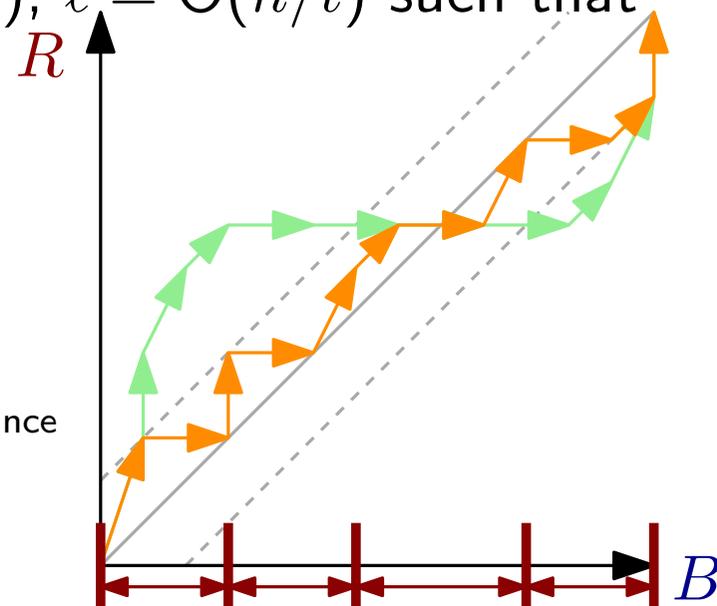
Theorem: For every $t > 0$, planar two-colored G with $V(G) = R \cup B$ and $|B| = |R|$, $V(G)$ partitions as (V_1, \dots, V_ℓ, X) , $\ell = \Theta(n/t)$ such that

- $|V_i \cup N(V_i)| = \Theta(t), \forall i.$
- X separates V_i from $V_j, (\forall i \neq j).$

- $|N(V_i)| = O(t^{3/4}), \forall i$

- $||V_i \cap R| - |V_i \cap B|| = O(\sqrt{t}), \forall i$

- compute **uniform** subdivision with $t' = \sqrt{t}$
- greedily create a permutation π of the pieces s.t. every prefix has imbalance at most $\pm c \cdot \sqrt{t}$
- break π into $\Theta(n/t)$ equal-sized intervals
- yields size $\Theta(t)$, boundary $O(t^{3/4})$, imbalance $O(\sqrt{t})$



From Nearly Balanced to Balanced Swaps

[this work]

Step 2: Obtain a **significantly profitable, almost balanced** swap

$$\min_i \frac{|L_i|}{|W_i|} \leq \frac{\sum_i |L_i|}{\sum_i |W_i|} \leq \frac{\text{ALG} - |Z|}{\text{OPT} - |Z|} \leq \frac{\text{ALG}}{\text{OPT}}$$

From Nearly Balanced to Balanced Swaps

[this work]

Step 2: Obtain a **significantly profitable, almost balanced** swap

elements **lost** by
swap out

$$\min_i \frac{|L_i|}{|W_i|} \leq \frac{\sum_i |L_i|}{\sum_i |W_i|} \leq \frac{\text{ALG} - |Z|}{\text{OPT} - |Z|} \leq \frac{\text{ALG}}{\text{OPT}}$$

1. swap out $V_i \cap \mathcal{S}$
2. swap in $(V_i \cup N(V_i)) \cap \mathcal{O}$

elements **won** by
swap in

elements staying
covered during
swaps

From Nearly Balanced to Balanced Swaps

[this work]

Step 2: Obtain a **significantly profitable, almost balanced** swap

$$\min_i \frac{|L_i|}{|W_i|} \leq \frac{\sum_i |L_i|}{\sum_i |W_i|} \leq \frac{\text{ALG} - |Z|}{\text{OPT} - |Z|} \leq \frac{\text{ALG}}{\text{OPT}}$$

assume $\text{ALG} < (1 - c/\sqrt{b})\text{OPT}$ where $b, t = b^2$, and c are large enough constants

\rightsquigarrow ex. i with $|L_i| < (1 - c/\sqrt{b})|W_i|$

From Nearly Balanced to Balanced Swaps

[this work]

Step 2: Obtain a **significantly profitable, almost balanced** swap

$$\min_i \frac{|L_i|}{|W_i|} \leq \frac{\sum_i |L_i|}{\sum_i |W_i|} \leq \frac{\text{ALG} - |Z|}{\text{OPT} - |Z|} \leq \frac{\text{ALG}}{\text{OPT}}$$

assume $\text{ALG} < (1 - c/\sqrt{b})\text{OPT}$ where b , $t = b^2$, and c are large enough constants

\rightsquigarrow ex. i with $|L_i| < (1 - c/\sqrt{b})|W_i|$

Step 3: Get **perfectly balanced, profitable** swap

From Nearly Balanced to Balanced Swaps

[this work]

Step 2: Obtain a **significantly profitable, almost balanced** swap

$$\min_i \frac{|L_i|}{|W_i|} \leq \frac{\sum_i |L_i|}{\sum_i |W_i|} \leq \frac{\text{ALG} - |Z|}{\text{OPT} - |Z|} \leq \frac{\text{ALG}}{\text{OPT}}$$

assume $\text{ALG} < (1 - c/\sqrt{b})\text{OPT}$ where $b, t = b^2$, and c are large enough constants

\rightsquigarrow ex. i with $|L_i| < (1 - c/\sqrt{b})|W_i|$

Step 3: Get **perfectly balanced, profitable** swap

$$S_j = \arg \max_{S \in \bar{O}_i} \left| S \setminus \left(Z_i \cup \bigcup_{\ell=1}^{j-1} S_\ell \right) \right|$$

S_1 maximizes $|S \setminus Z_i|$

From Nearly Balanced to Balanced Swaps

[this work]

Step 2: Obtain a **significantly profitable, almost balanced** swap

$$\min_i \frac{|L_i|}{|W_i|} \leq \frac{\sum_i |L_i|}{\sum_i |W_i|} \leq \frac{\text{ALG} - |Z|}{\text{OPT} - |Z|} \leq \frac{\text{ALG}}{\text{OPT}}$$

assume $\text{ALG} < (1 - c/\sqrt{b})\text{OPT}$ where $b, t = b^2$, and c are large enough constants

\rightsquigarrow ex. i with $|L_i| < (1 - c/\sqrt{b})|W_i|$

Step 3: Get **perfectly balanced, profitable** swap

$$S_j = \arg \max_{S \in \bar{O}_i} \left| S \setminus \left(Z_i \cup \bigcup_{\ell=1}^{j-1} S_\ell \right) \right| \quad \left| \left(\bigcup_{\ell=1}^j S_\ell \right) \setminus Z_i \right| \geq \frac{j \cdot |W_i|}{|\bar{O}_i|}. \quad (1)$$

S_1 maximizes $|S \setminus Z_i|$

From Nearly Balanced to Balanced Swaps

[this work]

Step 2: Obtain a **significantly profitable, almost balanced** swap

$$\min_i \frac{|L_i|}{|W_i|} \leq \frac{\sum_i |L_i|}{\sum_i |W_i|} \leq \frac{\text{ALG} - |Z|}{\text{OPT} - |Z|} \leq \frac{\text{ALG}}{\text{OPT}}$$

assume $\text{ALG} < (1 - c/\sqrt{b})\text{OPT}$ where $b, t = b^2$, and c are large enough constants

\rightsquigarrow ex. i with $|L_i| < (1 - c/\sqrt{b})|W_i|$

Step 3: Get **perfectly balanced, profitable** swap

$$\begin{aligned} |L_i| &< \left(1 - c/\sqrt{b}\right) \cdot |W_i| \\ &\leq \left(1 - c/\sqrt{b}\right) \frac{|\bar{O}_i|}{|\mathcal{A}_i|} \left| \left(\bigcup_{\ell=1}^{|\mathcal{A}_i|} S_\ell \right) \setminus Z_i \right| \\ &\leq \left| \left(\bigcup_{\ell=1}^{|\mathcal{A}_i|} S_\ell \right) \setminus Z_i \right|. \end{aligned}$$

From Nearly Balanced to Balanced Swaps

[this work]

Step 2: Obtain a **significantly profitable, almost balanced** swap

$$\min_i \frac{|L_i|}{|W_i|} \leq \frac{\sum_i |L_i|}{\sum_i |W_i|} \leq \frac{\text{ALG} - |Z|}{\text{OPT} - |Z|} \leq \frac{\text{ALG}}{\text{OPT}}$$

assume $\text{ALG} < (1 - c/\sqrt{b})\text{OPT}$ where $b, t = b^2$, and c are large enough constants

\rightsquigarrow ex. i with $|L_i| < (1 - c/\sqrt{b})|W_i|$

Step 3: Get **perfectly balanced, profitable** swap

$$\begin{aligned} |L_i| &< \left(1 - c/\sqrt{b}\right) \cdot |W_i| \\ &\leq \left(1 - c/\sqrt{b}\right) \frac{|\bar{O}_i|}{|\mathcal{A}_i|} \left| \left(\bigcup_{\ell=1}^{|\mathcal{A}_i|} S_\ell \right) \setminus Z_i \right| \\ &\leq \left| \left(\bigcup_{\ell=1}^{|\mathcal{A}_i|} S_\ell \right) \setminus Z_i \right|. \end{aligned}$$

\rightsquigarrow **balanced and profitable swap**

Overview and Future Work

Theorem: There is a PTAS for any class of max coverage problems that admits planar (f -separable) exchange graphs.

Corollary: Max coverage admits a PTAS for

confirms conjecture by Badanidiyuru, Kleinberg, Lee 2012

- covering points with halfspaces in \mathbb{R}^3
- covering points with pseudodisks in \mathbb{R}^2
- hitting pseudodisks (r -admissible regions) in \mathbb{R}^2 by points
- guarding 1.5D terrains
- maximum k -dominating set for intersection graphs of homothetic copies of convex objects (such as arbitrary squares, translated and scaled copies of convex objects)
- maximum k -dominating set on non-trivial minor-closed graph classes
- maximum k -vertex cover on f -separable on subgraph-closed graphclasses
- ...

Overview and Future Work

Theorem: There is a PTAS for any class of max coverage problems that admits planar (f -separable) exchange graphs.

Corollary: Max coverage admits a PTAS for

confirms conjecture by Badanidiyuru, Kleinberg, Lee 2012

- covering points with halfspaces in \mathbb{R}^3
 - covering points with pseudodisks in \mathbb{R}^2
 - hitting pseudodisks (r -admissible regions) in \mathbb{R}^2 by points
 - guarding 1.5D terrains
 - maximum k -dominating set for intersection graphs of homothetic copies of convex objects (such as arbitrary squares, translated and scaled copies of convex objects)
 - maximum k -dominating set on non-trivial minor-closed graph classes
 - maximum k -vertex cover on f -separable on subgraph-closed graphclasses
 - ...
- improve running time
 - improved ratios for APX-hard cases?
 - other applications (with hard cardinality constraint)?

Thank you!